



Institute of Automatic
Control and Robotics



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The thematic scope of the PCC 2026 includes but is not limited to:

- Linear and nonlinear feedback control design for dynamical systems
- Output feedback and observer design
- Optimal, stochastic, and constrained control
- Robust and adaptive autonomous systems under uncertainty
- Architectures of control systems
- Process diagnostics and fault tolerant control systems
- Stability and control performance analysis
- Safety, reliability and resilience issues in control systems
- Modelling and data-based identification of systems
- Sensing and measurement issues in automation and robotics
- Decision support and expert systems
- Machine learning methods and applications of artificial intelligence
- Human-machine cooperative control systems
- Control and perception systems for robots and autonomous vehicles
- Sensors, devices and tools in automation, control, and robotics
- Applications of control systems
- Automation for Industry 4.0, industrial control systems
- Social, educational, economic aspects of automatic control and robotics

IMPORTANT DATES:

- **September 2025:** Opening of a submission system
- **January 2026:** Deadline for submission of papers
- **March 2026:** Decision notification on submissions
- **April 2026:** Deadline for submission of revised papers

Presented papers will be published in the IEEE Xplore database.

The official language of the PCC 2026 is English.

Detailed instructions for authors are available on the PCC 2026 website:

<https://pcc2026.put.poznan.pl/>



Poznań University of Technology – the conference venue

Organizers are going to request the IEEE
for a technical co-sponsorship

**Conference under auspices of
the Committee of Automatic Control and
Robotics of the Polish Academy of Sciences**

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